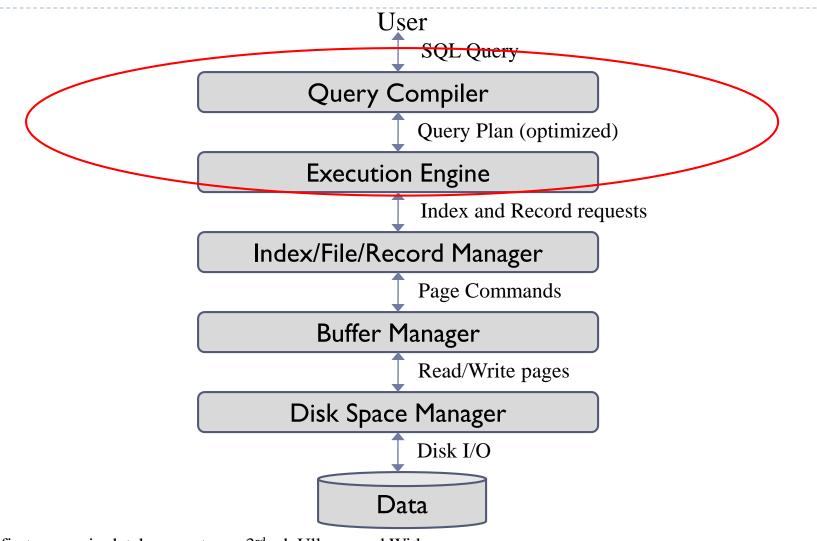
Query Evaluation Overview, cont.

Lecture 9 Feb. 29, 2016

Slides based on "Database Management Systems" 3rd ed, Ramakrishnan and Gehrke

Architecture of a DBMS



A first course in database systems, 3rd ed, Ullman and Widom

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The two major parts of the DB engine

- QP = query processor, top two boxes on last slide
- Storage manager = rest of boxes
- See "index and record requests" flowing between
- Can be more specific, see list, pg. 283:
- Actions on "files": file scan, search with equality selection, search with range selection, insert record, delete record
- Files listed: heap files, sorted files, clustered files, heap file with unclustered tree index, heap file with unclustered hash index.
 An index on its own is a sorted file.
- A file is something that the storage engine can process via an ISAM-like API
- A table can be accessed as a file: pick an index for it (or not)

Storage Engine API

- If a QP and storage engine hue to an API, then different storage engines can be "plugged in" to the database
- Example: MS SQL Server can access Excel files via the OLE-DB API. Also via ODBC.
 - That is, there is an Excel OLE-DB "provider" (you don't need the whole Excel GUI).
- Example: MySQL has various storage engines—MyISAM and Innodb, etc.
 - New one (Nov '12): ClouSE uses Amazon S3 cloud storage.

MySQL Storage Engine API

Top-level API (subset) from <u>internals manual</u> Note handoff to TABLE object for data actions:

```
int (*commit)(THD *thd, bool all);
int (*rollback)(THD *thd, bool all);
int (*prepare)(THD *thd, bool all);
int (*recover)(XID *xid_list, uint len);
handler *(*create)(TABLE *table); ←next slide
void (*drop_database)(char* path);
bool (*flush_logs)();
```

MySQL Storage Engine API: TABLE API

22.18.1 bas ext 22.18.2 close 22.18.3 create 22.18.4 delete row 22.18.5 delete table 22.18.6 external lock 22.18.7 extra 22.18.8 index end 22.18.9 index first 22.18.10 index init Set current index 22.18.11 index last Index 22.18.12 index next scan 22.18.13 index prev

Scan: iteration over rows, see "next" methods

22.18.14 index read 22.18.15 index read idx 22.18.16 index read last 22.18.17 info 22.18.18 open 22.18.19 position 22.18.20 records in range 22.18.21 rnd init Table 22.18.22 rnd next 22.18.23 rnd pos scan 22.18.24 start stmt 22.18.25 store lock 22.18.26 update row 22.18.27 write row Insert row

Access Paths

- An access path is a method of retrieving tuples:
 - File scan (AKA table scan if on a table)
 - Index scan using an index that matches a condition
- A tree index matches (a conjunction of) terms that involve every attribute in a prefix of the search key
 - E.g., tree index on <a, b, c> matches the selection a=5 AND b=3, and a=5 AND b>6, but not b=3
- A hash index matches (a conjunction of) terms attribute = value for every attribute in the search key of the index
 - E.g., hash index on <a, b, c> matches a=5 AND b=3 AND c=5
 - but it does not match b=3, or a=5 AND b=3

Example of matching indexes

Pg. 399: fix error Sailors → Reserves on line 8 Reserves (*sid*: integer, *bid*: integer, *day*: dates, *rname*: string) ← rname column added here

with indexes:

- Index I: Hash index on (rname, bid, sid)
 - Matches: rname='Joe' and bid = 5 and sid=3
 - Doesn't match: rname='Joe' and bid = 5
- Index2:Tree index on (rname, bid, sid)
 - Matches: rname='Joe' and bid = 5 and sid=3
 - Matches: rname='Joe' and bid = 5, also rname = 'Joe'
 - Doesn't match: bid = 5
- Index3:Tree index on (rname)
- Index4: Hash index on (rname)
 - These two match any conjunct with rname='Joe' in it

Executing Selections

- Find the *most selective access path*, retrieve tuples using it
 - Then, apply any remaining terms that don't match the index
- Most selective access path: index or file scan estimated to require the fewest page I/Os
 - Consider day<8/9/94 AND bid=5 AND sid=3</p>
- If we have B+ tree index on day, use that access path
 - Then, bid=5 and sid=3 must be checked for each retrieved tuple
 - day condition is primary conjunct
- Alternatively, use hash index on <bid, sid> first
 - Then, day<8/9/94 must then be checked</p>

Sailors (*sid*: integer, *sname*: string, *rating*: integer, *age*: real) Reserves (*sid*: integer, *bid*: integer, *day*: dates, *rname*: string)

- Similar to old schema; rname added
- Reserves:
 - 40 bytes long tuple, 100K records, 4KB pages
 - So I00K*40 = 4MB data, 4MB/4KB = 1000 pages
 - Assume 4000 bytes/pg, sol00 tuples per page
- Sailors:
 - 50 bytes long tuple, 40K tuples, 4KB pages
 - So 80 tuples per page, 500 pages

Using an Index for Selections

Cost influenced by:

- Number of qualifying tuples
- Whether the index is clustered or not
- Ex: SELECT *
 - FROM Reserves R

WHERE R.rname < 'C%'

- Assuming uniform distribution of names, 2/26 ~10% of tuples qualify, that is 10000 tuples (pg. 401)
 - With a clustered index, cost is little more 100 I/Os:
 - I0000*40 = 400KB data, in I00 data pages, plus a few index pgs
 - If not clustered, up to I 0K I/Os!
 - About 10000 data pages accessed, each with own I/O (unless big enough buffer pool)
 - Better to do a table scan: 1000 pages, so 1000 I/Os.

Executing Projections

Expensive part is removing duplicates

DBMS don't remove duplicates unless DISTINCT is specified

SELECT **DISTINCT** R.sid, R.bid FROM Reserves R

Sorting Approach

- Sort on <sid, bid> (or <bid, sid>) and remove duplicates
- Avoidable if an index with R.sid and R.bid in the search key exists

Hashing Approach

- Hash on <sid, bid> to create partitions (buckets)
- Load partitions into memory one at a time, build in-memory hash structure, and eliminate duplicates

Executing Joins: Index Nested Loops

for each tuple r in R do for each tuple s in S where $r_i == s_j$ do add <r, s> to result

- Cost = (M*p_R) * (cost of finding matching inner-table tuples)
- M = number of pages of R, p_R = number of R tuples per page
- If relation has index on join attribute, make it inner relation
 - For each outer tuple, cost of probing inner index is 1.2 for hash index, 2-4 for B+, plus cost to retrieve matching S tuples
 - Clustered index typically single I/O no more I/O (unless many matching S tuples)
 - Unclustered index | I/O per matching S tuple

Duplicate keys in indexes

- B trees: see Sec. 10.7 Duplicates: two ways to go-
 - Overflow pages, but not "typical"
 - Just sequential entries with the same key (we'll assume this)
- Extendible Hashing: uses overflow pages (pg. 379)
- Linear Hashing: uses multiple entries in the main pages.
 - May involve "extra" overflow pages, since splitting doesn't help with a long sequence of same-key entries.
- Shouldn't use a hash index on a low-cardinality column. Btree is OK (esp. Alt. 3). (Bitmap index is best.)
- Cost of access for all dups of one key: calculate number of pages of duplicate index entries

Example of Index Nested Loops (1/2)

Example: Reserves JOIN Sailors (natural join on sid)

Case I: Hash-index (Alternative 2) on sid of Sailors

- Choose Sailors as inner relation
- Scan Reserves: 100K tuples, 1000 page I/Os
- For each Reserves tuple
 - 1.2 I/Os to get data entry in index (see pg. 412)
 - 1 I/O to get (the exactly one) matching Sailors tuple (primary key)
- Total: 221,000 I/Os

Example of Index Nested Loops (2/2)

Example: Reserves JOIN Sailors (natural join on sid)

Case 2: Hash-index (Alternative I or 2) on sid of Reserves

- Choose Reserves as inner
- Scan Sailors: 40K tuples, 500 page I/Os
- For each Sailors tuple
 - 1.2 I/Os to find index page with data entries
 - Assuming uniform distribution, 2.5 matching records per sailor
 - Cost of retrieving records is nothing further (Alt. I, clustered) or
 2.5 I/Os (Alt. 2)
- Total: 88,500 I/Os (clustered) or 148,500 I/Os (unclustered)

Executing Joins: Sort-Merge

- Sort R and S on the join column
 - Then scan them to do a merge on join column
- R is scanned once
- Each S group is scanned once per matching R tuple
 - Multiple scans per group needed only if S records with same join attribute value span multiple pages
 - Multiple scans of an S group are likely to find needed pages in buffer
- Cost: M log M + N log N + (M+N)
 - The cost of scanning, M+N, could be M*N worst case (very unlikely!)

System R Optimizer

Developed at IBM starting in the 1970's

Most widely used currently; works well for up to 10 joins

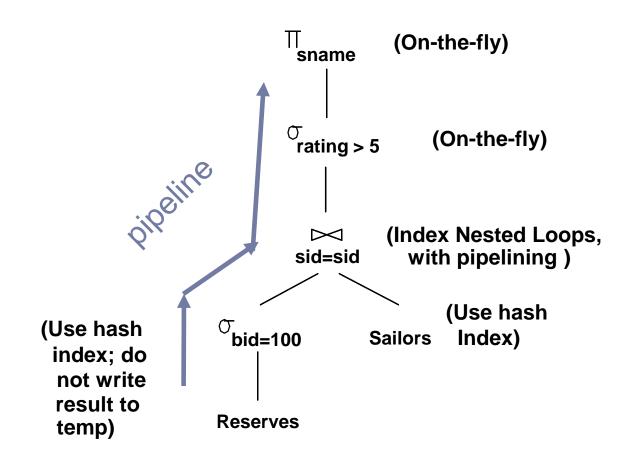
Cost estimation

- Statistics maintained in system catalogs
- Used to estimate cost of operations and result sizes
- Considers combination of CPU and I/O costs
- Query Plan Space
 - Only the space of left-deep plans is considered
 - Cartesian products avoided

Left Deep Trees

- Consider nested-loop joins
- Inner tables need to be materialized because they are probed repeatedly for each row of the outer table
 - Materialized means available as a table, not just a stream of rows, so can be probed by PK index.
- Left table = outer table
- Left table can be pipelined: rows used one at a time in order (i.e., doesn't need to be materialized)
- So Left-deep plans allow output of each operator to be pipelined into the next operator without storing it in a temporary relation
- i.e., Left Deep trees can be "fully pipelined"

Example of join with left table pipelined and right table materialized



Cost Estimation

For each plan considered, must estimate:

- Cost of each operator in plan tree
 - Depends on input cardinalities
 - Operation and access type: sequential scan, index scan, joins
- Size of result for each operation in tree
 - Use information about the input relations
 - For selections and joins, assume independence of predicates

Size Estimation and Reduction Factors

SELECT attribute list FROM relation list WHERE term₁ AND ... AND term_k

- Maximum number of tuples is cardinality of cross product
- Reduction factor (RF) associated with each term reflects its impact in reducing result size
 - Implicit assumption that terms are independent!
 - col = value has RF =1/NKeys(I), given index I on col
 - col1 = col2 has RF = 1/max(NKeys(l1), NKeys(l2))
 - col > value has RF = (High(I)-value)/(High(I)-Low(I))

Sailors (*sid*: integer, *sname*: string, *rating*: integer, *age*: real) Reserves (*sid*: integer, *bid*: integer, *day*: dates, *rname*: string)

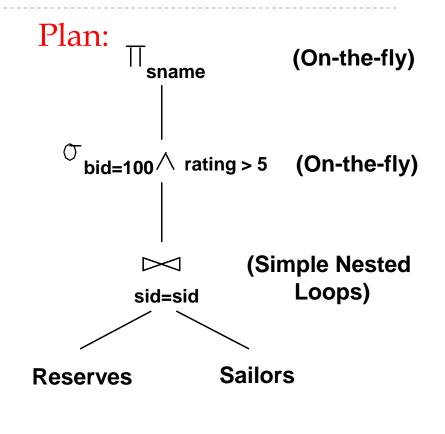
- Similar to old schema; rname added
- Reserves:
 - 40 bytes long tuple, 100K records, 100 tuples per page, 1000 pages
- Sailors:
 - ▶ 50 bytes long tuple, 40K tuples, 80 tuples per page, 500 pages

Evaluation Example

SELECT S.sname FROM Reserves R, Sailors S WHERE R.sid=S.sid AND R.bid=100 AND S.rating>5

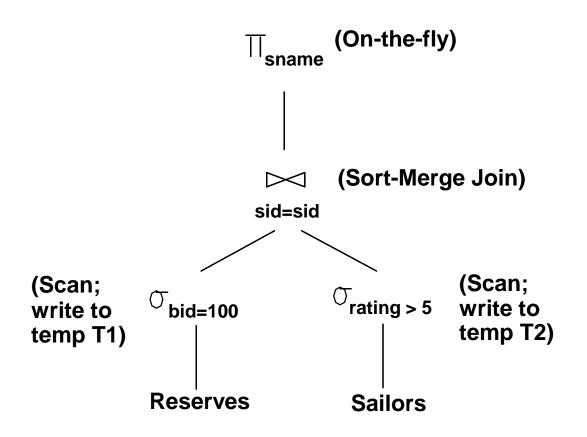
Cost: 1000+500*1000 I/Os

- By no means the worst plan!
- Misses several opportunities:
 - Selections could have been `pushed' earlier
 - No use of any available indexes



Alternative Plan 1 (No Indexes)

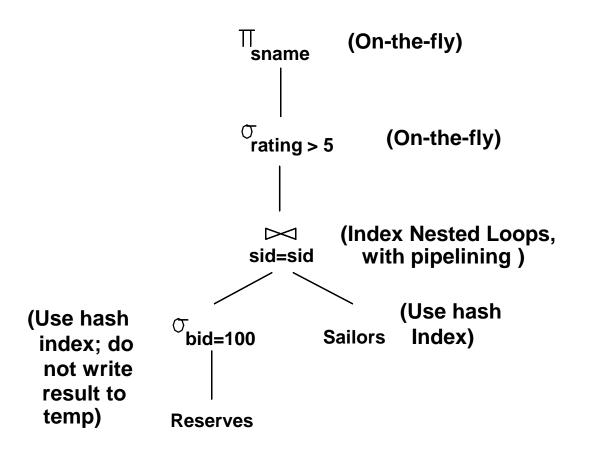
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Alternative Plan 1 (No Indexes)

- Main difference: push down selections
- Scan Reserves (1000) + write temp T1 (10 pages, if we have 100 boats, uniform distribution)
- Scan Sailors (500) + write temp T2 (250 pages, if we have 10 ratings)
- Sort-merge join TI and T2
 - Assume there are 5 buffers:
 - Sort T1 (2*2*10), Sort T2 (2*4*250), Merge (10+250)
 - Total: 4060 page I/Os

Alternative Plan 2 (With Indexes)



Alternative Plan 2 (With Indexes)

- With clustered index on *bid* of Reserves, we get 100,000/100 = 1000 tuples on 1000/100 = 10 pages
- Inner Nested Loop join with pipelining (result not materialized)
- Join column sid is a key for Sailors
 - > At most one matching tuple, unclustered index on sid OK
- Decision not to push rating>5 before the join is based on availability of sid index on Sailors
- Cost:
 - Selection of Reserves tuples 10 I/Os
 - For each, must get matching Sailors tuple (1000*1.2)
 - Total 1210 I/Os

Summary

- There are several alternative evaluation algorithms for each relational operator.
- A query is evaluated by converting it to a tree of operators and evaluating the operators in the tree.
- Must understand query optimization in order to fully understand the performance impact of a given database design (relations, indexes) on a workload (set of queries).
- Two parts to optimizing a query:
 - Consider a set of alternative plans.
 - Must prune search space; typically, left-deep plans only.
 - Must estimate cost of each plan that is considered.
 - Must estimate size of result and cost for each plan node.
 - Key issues: Statistics, indexes, operator implementations.