

# CS 444 Operating Systems

## Chapter 6 Deadlocks

J. Holly DeBlois

March 6, 2025

# Resources to be Shared

- Hardware devices
- Software resources
  - A piece of information
  - Database records
- Preemptable
  - RAM
- Nonpreemptable
  - Printer, tape drive

# Use a Semaphore to Protect Resources

- One resource

```
typedef int semaphore;  
semaphore resource_1;
```

```
void process_A(void) {  
    down(&resource_1);  
    use_resource_1( );  
    up(&resource_1);  
}
```

(a)

- Two resources

```
typedef int semaphore;  
semaphore resource_1;  
semaphore resource_2;
```

```
void process_A(void) {  
    down(&resource_1);  
    down(&resource_2);  
    use_both_resources( );  
    up(&resource_2);  
    up(&resource_1);  
}
```

(b)

# A Potential Deadlock

- Deadlock-free

```
typedef int semaphore;  
semaphore resource_1;  
semaphore resource_2;  
  
void process_A(void) {  
    down(&resource_1);  
    down(&resource_2);  
    use_both_resources( );  
    up(&resource_2);  
    up(&resource_1);  
}  
  
void process_B(void) {  
    down(&resource_1);  
    down(&resource_2);  
    use_both_resources( );  
    up(&resource_2);  
    up(&resource_1);  
}
```

(a)

- A potential deadlock

```
semaphore resource_1;  
semaphore resource_2;  
  
void process_A(void) {  
    down(&resource_1);  
    down(&resource_2);  
    use_both_resources( );  
    up(&resource_2);  
    up(&resource_1);  
}  
  
void process_B(void) {  
    down(&resource_2);  
    down(&resource_1);  
    use_both_resources( );  
    up(&resource_1);  
    up(&resource_2);  
}
```

(b)

# Deadlock Definition

- A set of processes is deadlocked if
  - 1 Each process in the set is waiting for an event
  - 2 That event can be caused only by another process in the set

# Conditions for Resource Deadlock

- Four conditions must hold
  - 1 Mutual exclusion
  - 2 Hold and wait
  - 3 No preemption
  - 4 Circular wait

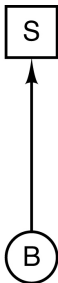
# Resource Allocation Graph

- Holding a resource



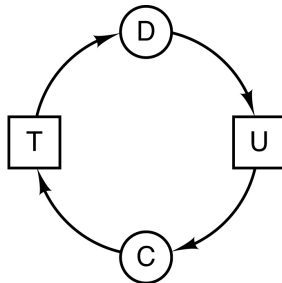
(a)

- Requesting a resource



(b)

- Deadlock

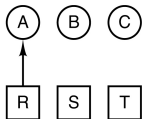


(c)

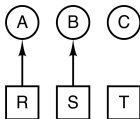
# An Example of Circular Wait

1. A requests R
2. B requests S
3. C requests T
4. A requests S
5. B requests T
6. C requests R  
deadlock

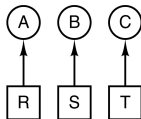
(d)



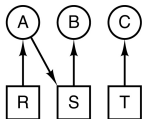
(e)



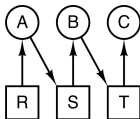
(f)



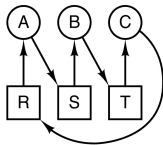
(g)



(h)



(i)



(j)

- A, B, and C are in circular wait

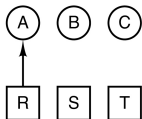


# Holding Process B Back

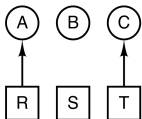
- Hold process B back to break up the cycle

1. A requests R
2. C requests T
3. A requests S
4. C requests R
5. A releases R
6. A releases S  
no deadlock

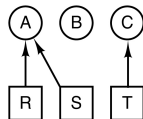
(k)



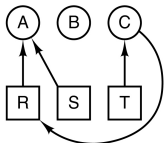
(l)



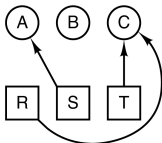
(m)



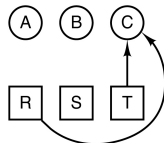
(n)



(o)



(p)



(q)

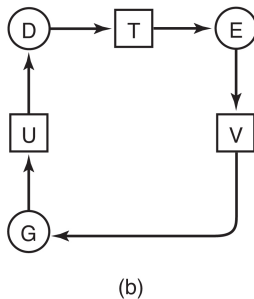
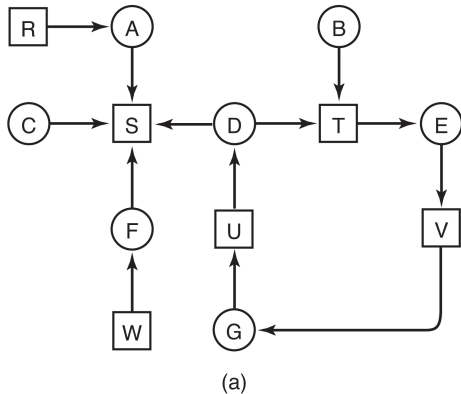
# Strategies for Dealing with Deadlocks

- Ignore the problem — maybe it will go away
  - The ostrich algorithm
  - The current strategy used in most systems
- Detection and recovery
  - Let deadlocks occur, detect them, and take action
- Dynamic avoidance
  - Careful resource allocation
- Prevention
  - Structurally negating one of the four required conditions

# Deadlock Detection

- A resource graph

- A cycle extracted from the graph



# DFS to Detect Deadlocks

- For each node  $N$  in the graph, perform these steps with  $N$  as the current node
  - 1 Initialize  $S$  to an empty stack and designate all edges as unmarked
  - 2 Push the current node into  $S$ , check if the node appears in  $S$  twice
    - If yes, the graph has a cycle (listed in  $S$ ) and thus a deadlock
  - 3 If the current node has any unmarked outgoing edges, go to step 4; if not, go to step 5
  - 4 Pick an unmarked outgoing edge, mark it and follow it to the new current node; go to step 2
  - 5 If this is initial node, the graph does not contain cycles and no deadlocks. Otherwise, pop the node from  $S$  and go back to the previous node


# When There Are Multiple Resources of Each Type

- The previous deadlock detection algorithm works with the assumption that there is just one resource of each type
- Often a computer has multiple resources of each type
- Use four data structures to support deadlock detection when multiple resources are available

# Four Data Structures

Resources in existence  
( $E_1, E_2, E_3, \dots, E_m$ )


Current allocation matrix


$$\begin{bmatrix} C_{11} & C_{12} & C_{13} & \cdots & C_{1m} \\ C_{21} & C_{22} & C_{23} & \cdots & C_{2m} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ C_{n1} & C_{n2} & C_{n3} & \cdots & C_{nm} \end{bmatrix}$$

Row n is current allocation  
to process n

Resources available  
( $A_1, A_2, A_3, \dots, A_m$ )

Request matrix


$$\begin{bmatrix} R_{11} & R_{12} & R_{13} & \cdots & R_{1m} \\ R_{21} & R_{22} & R_{23} & \cdots & R_{2m} \\ \vdots & \vdots & \vdots & \cdots & \vdots \\ R_{n1} & R_{n2} & R_{n3} & \cdots & R_{nm} \end{bmatrix}$$

Row 2 is what process 2 needs

# Deadlock Detection Algorithm

- 1 Look for an unmarked process  $P_i$  for which the  $i$ -th row of  $R$  (request) is less than or equal to  $A$  (available)
  - This process can acquire all resources it needs for successful completion
- 2 If such a process is found, add the  $i$ -th row of  $C$  (current allocation) to  $A$ , mark the process, go back to step 1
  - Pretend this process has finished and releases its acquired resources
- 3 If no such process exists, algorithm terminates
  - The unmarked processes are in a deadlock

# Example

$$E = \begin{pmatrix} 4 & 2 & 3 & 1 \end{pmatrix}$$

Tape drives  
Plotters  
Scanners  
Blu-rays

$$A = \begin{pmatrix} 2 & 1 & 0 & 0 \end{pmatrix}$$

Tape drives  
Plotters  
Scanners  
Blu-rays

Current allocation matrix

$$C = \begin{bmatrix} 0 & 0 & 1 & 0 \\ 2 & 0 & 0 & 1 \\ 0 & 1 & 2 & 0 \end{bmatrix}$$

Request matrix

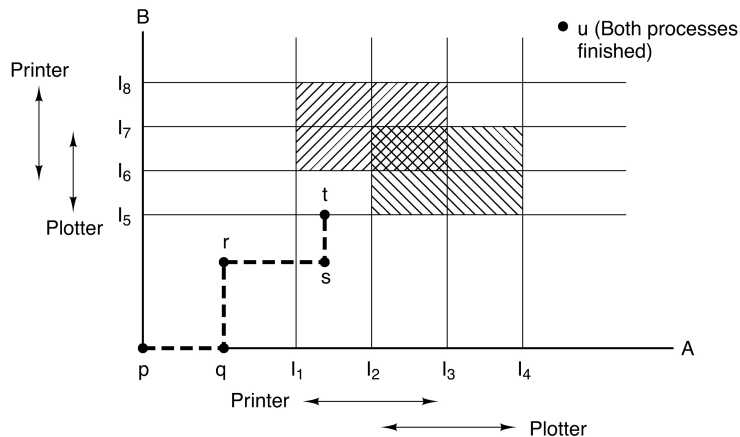
$$R = \begin{bmatrix} 2 & 0 & 0 & 1 \\ 1 & 0 & 1 & 0 \\ 2 & 1 & 0 & 0 \end{bmatrix}$$



# Recovery from Deadlock

- Possible methods of recovery, although none are “attractive”:
- Preemption
- Rollback
  - Checkpoints
- Killing processes

# Resource Trajectories



- Two processes make requests for printer and plotter
- Avoid deadlock by following viable trajectories

# Safe and Unsafe States

	Has	Max
A	3	9
B	2	4
C	2	7

Free: 3  
(a)

	Has	Max
A	3	9
B	4	4
C	2	7

Free: 1  
(b)

	Has	Max
A	3	9
B	0	–
C	2	7

Free: 5  
(c)

	Has	Max
A	3	9
B	0	–
C	7	7

Free: 0  
(d)

	Has	Max
A	3	9
B	0	–
C	0	–

Free: 7  
(e)

- The state in (a) is safe because
- Process B can get all it needs, finish, and release resources
- Then process C can finish
- Then process A can finish

# Safe and Unsafe States

Has Max

A	3	9
B	2	4
C	2	7

Free: 3

(a)

Has Max

A	4	9
B	2	4
C	2	7

Free: 2

(b)

Has Max

A	4	9
B	4	4
C	2	7

Free: 0

(c)

Has Max

A	4	9
B	Đ	Đ
C	2	7

Free: 4

(d)

- The state in (a) is safe
- The state in (b) is not safe

# Banker's Algorithm for Single Resource

Has Max

	Has	Max
A	0	6
B	0	5
C	0	4
D	0	7

Free: 10

(a)

Has Max

	Has	Max
A	1	6
B	1	5
C	2	4
D	4	7

Free: 2

(b)

Has Max

	Has	Max
A	1	6
B	2	5
C	2	4
D	4	7

Free: 1

(c)

- The state in (a) is safe
- The state in (b) is safe
- The state in (c) is not safe

# Banker's Algorithm for Multiple Resources

Process	Tape drives	Plotters	Printers	Blu-rays
A	3	0	1	1
B	0	1	0	0
C	1	1	1	0
D	1	1	0	1
E	0	0	0	0

Resources assigned

Process	Tape drives	Plotters	Printers	Blu-rays
A	1	1	0	0
B	0	1	1	2
C	3	1	0	0
D	0	0	1	0
E	2	1	1	0

Resources still assigned

$E = (6342)$   
 $P = (5322)$   
 $A = (1020)$

- 2 tables: current allocation, future need
- 3 vectors: total in existence E, present allocation P, available A

# Banker's Algorithm

- 1 Look for a process  $S$  whose unmet resource needs are all smaller than or equal to  $A$ 
  - If no such process exists, the system will eventually deadlock
- 2 Assume  $S$  requests all resources needed and finishes, mark  $S$  as terminated, return its resources to the vector  $A$
- 3 Repeat steps 1 and 2 until
  - 1 Either all processes are marked terminated (safe state)
  - 2 Or no process is left whose resource needs can be met (deadlock)

# Deadlock Prevention

- Assure that at least one of conditions is never satisfied
- ① Mutual exclusion
- ② Hold and wait
- ③ No Preemption
- ④ Circular wait

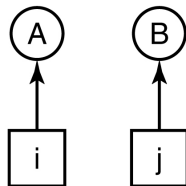
Condition	Approach
Mutual exclusion	Spool everything
Hold and wait	Request all resources initially
No preemption	Take resources away
Circular wait	Order resources numerically



# Prevent Circular Wait

1. Imagesetter
2. Printer
3. Plotter
4. Tape drive
5. Blu-ray drive

(a)



(b)

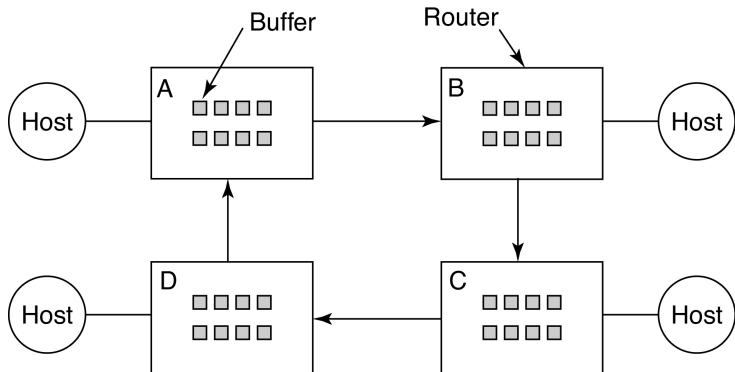
- Numerically ordered resources
- Request resources monotonically

# Communication Deadlock

- Cooperation synchronization
  - Send/receive acknowledgment
  - Lost acknowledgment
- Competition synchronization

# Communication Deadlock

- A deadlock in a network



# Livelock

```
void process_A(void) {
    acquire_lock(&resource_1);
    while (try_lock(&resource_2) == FAIL) {
        release_lock(&resource_1);
        wait_fixed_time();
        acquire_lock(&resource_1);
    }
    use_both_resources( );
    release_lock(&resource_2);
    release_lock(&resource_1);
}
```

```
void process_A(void) {
    acquire_lock(&resource_2);
    while (try_lock(&resource_1) == FAIL) {
        release_lock(&resource_2);
        wait_fixed_time();
        acquire_lock(&resource_2);
    }
    use_both_resources( );
    release_lock(&resource_1);
    release_lock(&resource_2);
}
```

- Processes are not strictly blocked, but they are not going anywhere
- Compete for process table entries
- Compete for file table entries